

State University of New York

EECE 301 Signals & Systems Prof. Mark Fowler

<u>Note Set #15</u>

- C-T Signals: Fourier Transform Properties
- Reading Assignment: Section 3.6 of Kamen and Heck

Course Flow Diagram

The arrows here show conceptual flow between ideas. Note the parallel structure between the pink blocks (C-T Freq. Analysis) and the blue blocks (D-T Freq. Analysis).



Fourier Transform Properties

Note: There are a few of these we won't cover.... see **Table on Website** or the inside front cover of the book for them.

I prefer that you use the tables on the website... they are better than the book's

As we have seen, finding the FT can be <u>tedious</u> (it can even be <u>difficult</u>)

But...there are certain properties that can often make things easier.

- Also, these properties can sometimes be the key to understanding how the FT can be used in a given application.
- So... even though these results may at first seem like "just boring math" they are important tools that let signal processing engineers understand how to build things like cell phones, radars, mp3 processing, etc.

1. Linearity (Supremely Important)

Gets used virtually all the time!!

If
$$x(t) \leftrightarrow X(\omega)$$
 & $y(t) \leftrightarrow Y(\omega)$

then
$$[ax(t) + by(t)] \leftrightarrow [aX(\omega) + bY(\omega)]$$

Another way to write this property:

 $\mathscr{F}\left\{ax(t)+by(t)\right\}=a\mathscr{F}\left\{x(t)\right\}+b\mathscr{F}\left\{y(t)\right\}$

To see why:
$$\Im \{ax(t) + by(t)\} = \int_{-\infty}^{\infty} [ax(t) + by(t)]e^{-j\omega t} dt$$
 Use Defn of FT



Example Application of "Linearity of FT": Suppose we need to find the FT of the following signal...



Finding this using straight-forward application of the definition of FT is not difficult but it is tedious:

$$\mathscr{F}\left\{x(t)\right\} = \int_{-2}^{-1} e^{-j\omega t} dt + 2\int_{-1}^{1} e^{-j\omega t} dt + \int_{1}^{2} e^{-j\omega t} dt$$

So... we look for short-cuts:

- One way is to recognize that each of these integrals is basically the same
- Another way is to break *x*(*t*) down into a sum of signals on our table!!!

Break a complicated signal down into simple signals before finding FT:



Mathematically we write: $x(t) = p_4(t) + p_2(t)$ \longrightarrow $X(\omega) = P_4(\omega) + P_2(\omega)$

From FT Table we have a known result for the FT of a pulse, so...

$$X(\omega) = 4\operatorname{sinc}\left(\frac{2\omega}{\pi}\right) + 2\operatorname{sinc}\left(\frac{\omega}{\pi}\right)$$

2. Time Shift (Really Important!) Used often to understand <u>practical</u> issues that arise in <u>audio</u>, <u>communications</u>, <u>radar</u>, etc.

If $x(t) \leftrightarrow X(\omega)$ then $x(t-c) \leftrightarrow X(\omega)e^{-jc\omega}$

<u>Note</u>: If c > 0 then x(t - c) is a <u>delay</u> of x(t)

So... what does this *mean*??

<u>First</u>... it does nothing to the magnitude of the FT: $|X(\omega)e^{-j\omega c}| = |X(\omega)|$

That means that a shift doesn't change "how much" we need of each of the sinusoids we build with

<u>Second</u>... it does change the <u>phase</u> of the FT: $\angle \{X(\omega)e^{-jc\omega}\} = \angle X(\omega) + \angle e^{-jc\omega}$

 $= \angle X(\omega) + c\omega$

This gets added to original phase

Phase shift increases linearly as the frequency increases

Line of slope -c

Shift of Time Signal ⇔ "Linear" Phase Shift of Frequency Components

Example Application of Time Shift Property: Room acoustics.

<u>Practical Questions</u>: Why do some rooms sound bad? Why can you fix this by using a "graphic equalizer" to "boost" some frequencies and "cut" others?

Very simple case of a <u>single</u> reflection:



So... You hear: $y(t) = x(t) + \alpha x(t-c)$ instead of just x(t)

Use linearity and time shift to get the FT at your ear: $Y(\omega) = \Im\{x(t) + \alpha x(t-c)\} = \Im\{x(t)\} + \alpha \Im\{x(t-c)\}$

$$= X(\omega) + \alpha X(\omega)e^{-j\omega \omega}$$

$$Y(\omega) = X(\omega) \left[1 + \alpha e^{-j\omega x} \right]$$

This is the FT of what you hear...

It gives an equation that shows how the reflection affects what you hear!!!!



The big picture... revisited:





Effect of the room... what does it look like as a function of frequency?? The cosine term makes it wiggle up and down... and the value of c controls how fast it wiggles up and down

Spacing = 1/c Hz

"Dip-to-Dip" "Peak-to-Peak" c controls spacing between dips/peaks

 α controls depth/height of dips/peaks

The next 3 slides explore these effects

<u>What is a typical value for delay *c*???</u> Speed of sound in air \approx 340 m/s

Typical difference in distance ≈ 0.167 m

$$c = \frac{0.167 \text{m}}{340 \text{m/s}} = 0.5 \text{msec}$$

• Spacing =
$$2 \text{ kHz}$$

Attenuation: $\alpha = 0.2$ Delay: c = 0.5 ms (Spacing = 1/0.5e-3 = 2 kHz)



Longer delay causes closer spacing... so more dips/peaks over audio range!

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Attenuation: $\alpha = 0.8$ Delay: c = 0.5 ms (Spacing = 1/0.5e-3 = 2 kHz)



Stronger reflection causes bigger boosts/cuts!!





Shorter delay causes wider spacing... so fewer dips/peaks over audio range!

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function room_delay(atten,delay)

f=0:100:20000; % Freq range: 0 Hz to 20 kHz w=2*pi*f; % convert to rad/sec

H=abs(1 + atten*exp(-j*w*delay)); % Compute Room Effect

```
% Make up a fictitious audio spectrum X=50000*w./((2*pi*2000+w)).^2;
```

```
% Now do plots
subplot(3,1,1) % splits figure into 3 subplots, pick 1<sup>st</sup> one
plot(f/1000,X) % note f converted into k Hz
xlabel('f (kHz)')
ylabel('Original Audio Spectrum')
axis([0 20 0 2]) % set axis ranges as desired
grid % put grid lines on
```

```
subplot(3,1,2) % splits figure into 3 subplots, pick 2<sup>nd</sup> one
plot(f/1000,H)
xlabel('f (kHz)')
ylabel('Room Effect')
axis([0 20 0 2])
grid
```

```
subplot(3,1,3) % splits figure into 3 subplots, pick 3<sup>rd</sup> one
plot(f/1000,H.*X)
xlabel('f (kHz)')
ylabel('Changed Audio Spectrum')
axis([0 20 0 2])
grid
```



<u>3. Time Scaling (Important)</u>

Q: If $x(t) \leftrightarrow X(\omega)$, then $x(at) \leftrightarrow ???$ for $a \neq 0$



An interesting "duality"!!!

To explore this FT property...first, what does *x*(*at*) look like?



|a| < 1 makes it "wiggle" slower \Rightarrow need <u>less</u> high frequencies







<u>Rough</u> Rule of Thumb we can extract from this property:

↑ Duration $\Rightarrow \downarrow$ Bandwidth

 \downarrow Duration \Rightarrow \uparrow Bandwidth

Very Short Signals *tend* to take up Wide Bandwidth

<u>4. Time Reversal</u> (Special case of time scaling: a = -1)

$$\underbrace{x(-t) \leftrightarrow X(-\omega)}_{\text{Outber }} \text{ double conjugate}$$

$$\underbrace{\text{Note: } X(-\omega) = \int_{-\infty}^{\infty} x(t)e^{-j(-\omega)t}dt = \int_{-\infty}^{\infty} x(t)e^{+j\omega t}dt = \text{``No Change''}$$

$$= \int_{-\infty}^{\infty} \overline{x(t)}e^{+j\omega t} dt$$

Conjugate changes to $-j$
$$= x(t) \text{ if } x(t) \text{ is real}$$

$$=\int_{-\infty}^{\infty}x(t)e^{-j\omega t}dt=\overline{X(\omega)}$$

So if x(t) is <u>real</u>, then we get the <u>special case</u>:

 $x(-t) \leftrightarrow X(\omega)$

<u>Recall</u>: conjugation doesn't change abs. value but negates the angle

$$\left|\overline{X(\omega)}\right| = \left|X(\omega)\right|$$

5. Multiply signal by *tⁿ*

$$t^n x(t) \leftrightarrow (j)^n \frac{d^n X(\omega)}{d\omega^n}$$
 $n = \text{positive integer}$

This property is mostly useful for finding the FT of typical signals.



So... we can use this property as follows:

$$X(\omega) = j \frac{d}{d\omega} P_2(\omega) = j \frac{d}{d\omega} \left(2 \operatorname{sinc} \left(\frac{\omega}{\pi} \right) \right)$$

$$= j 2 \left[\frac{\omega \cos(\omega) - \sin(\omega)}{\omega^2} \right]$$
Now... how do you get the derivative of the sinc???
Use the definition of sinc and then use the rule for the derivative of a quotient you learned in Calc I:

$$\frac{d}{dx} \left[\frac{f(x)}{g(x)} \right] = \frac{g(x) \frac{df(x)}{dx} - f(x) \frac{dg(x)}{dx}}{g^2(x)}$$

<u>6. Modulation Property</u> Super important!!! <

Essential for understanding <u>practical</u> issues that arise in <u>communications, radar</u>, etc.

There are two forms of the modulation property...

- 1. Complex Exponential Modulation ... simpler mathematics, doesn't <u>directly</u> describe real-world cases
- 2. Real Sinusoid Modulation... mathematics a bit more complicated, directly describes real-world cases

Euler's formula connects the two... so you often can use the Complex Exponential form to analyze real-world cases

Complex Exponential Modulation Property

$$x(t)e^{j\omega_0 t} \leftrightarrow X(\omega - \omega_0)$$

Multiply signal by a complex sinusoid

Shift the FT in frequency







Real Sinusoid Modulation

Based on Euler, Linearity property, & the Complex Exp. Modulation Property



Interesting... This tells us how to move a signal's spectrum up to higher frequencies without changing the shape of the spectrum!!!

What is that good for??? Well... only <u>high</u> frequencies will radiate from an antenna and propagate as electromagnetic waves and then induce a signal in a receiving antenna....

Application of Modulation Property to Radio Communication

FT theory tells us what we need to do to make a <u>simple</u> radio system... <u>then</u> electronics can be built to perform the operations that the FT theory calls for:



Cell Phones: around 900 MHz, around 1.8 GHz, around 1.9 GHz etc.

The next several slides show how these ideas are used to make a receiver:







So... what have we seen in this example:

Using the Modulation property of the FT we saw...

- 1. Key Operation at Transmitter is up-shifting the message spectrum:
 - a) FT Modulation Property tells the theory then we can build...
 - b) "modulator" = oscillator and a multiplier circuit
- 2. Key Operation at Transmitter is down-shifting the received spectrum
 - a) FT Modulation Property tells the theory then we can build...
 - b) "de-modulator" = oscillator and a multiplier circuit
 - c) But... the FT modulation property theory also shows that we need filters to get rid of "extra spectrum" stuff
 - i. So... one thing we still need to figure out is how to deal with these filters...
 - ii. Filters are a specific "system" and we still have a lot to learn about Systems...
 - iii. That is the subject of much of the rest of this course!!!

<u>7. Convolution Property</u> (The Most Important FT Property!!!)

The ramifications of this property are the subject of the <u>entire</u> Ch. 5 and continues into <u>all</u> the other chapters!!!

It is this property that makes us study the FT!!

Mathematically we state this property like this:

$$x(t) * h(t) \iff X(\omega)H(\omega)$$

Another way of stating this is:

$$\mathscr{F}\left\{x(t) * h(t)\right\} = X(\omega)H(\omega)$$

Now... what does this mean and why is it so important??!!

Recall that convolution is used to described what comes out of an LTI system:

$$x(t) \qquad y(t) = x(t) * h(t)$$

Now we can take the FT of the input and the output to see how we can view the system behavior "in the frequency domain":



It is easier to think about and analyze the operation of a system using this "frequency domain" view because visualizing multiplication is easier than visualizing convolution

Let's revisit our "Room Acoustics" example:



So, we fix it by putting in an "equalizer" (a system that fixes things)



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Equalizer's $|H_{eq}(\omega)|$ should peak at frequencies where the room's $|H_{room}(\omega)|$ dips and vice versa



8. Multiplication of Signals

$$x(t)y(t) \leftrightarrow \frac{1}{2\pi} X(\omega) * Y(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\lambda) Y(\omega - \lambda) d\lambda$$

This is the "dual" of the convolution property!!!







Generalized Parseval's Theorem:

$$\int_{-\infty}^{\infty} x(t) \overline{y(t)} dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \overline{Y(\omega)} d\omega$$



Both FT & IFT are pretty much the "<u>same</u> machine": $c \int_{-\infty}^{\infty} f(\lambda) e^{\pm j\lambda\xi} d\lambda$

So if there is a "time-to-frequency" property we would expect a virtually similar "frequency-to-time" property

 Illustration: Delay Property:
 $x(t-c) \leftrightarrow X(\omega)e^{-j\omega c}$

 Modulation Property:
 $x(t)e^{j\omega_0 t} \leftrightarrow X(\omega - \omega_0)$

Other Dual Properties:(Multiply by t^n) vs. (Diff. in time domain)(Convolution)vs. (Mult. of signals)

Also, this duality structure gives FT pairs that show duality.

Suppose we have a FT table that a FT Pair A... we can get the dual Pair B using the general Duality Property:

- 1. Take the FT side of (known) Pair A and replace ω by *t* and move it to the time-domain side of the table of the (unknown) Pair B.
- 2. Take the time-domain side of the (known) Pair A and replace *t* by $-\omega$, multiply by 2π , and then move it to the FT side of the table of the (unknown) Pair B.

Here is an example... We found the FT pair for the pulse signal:

