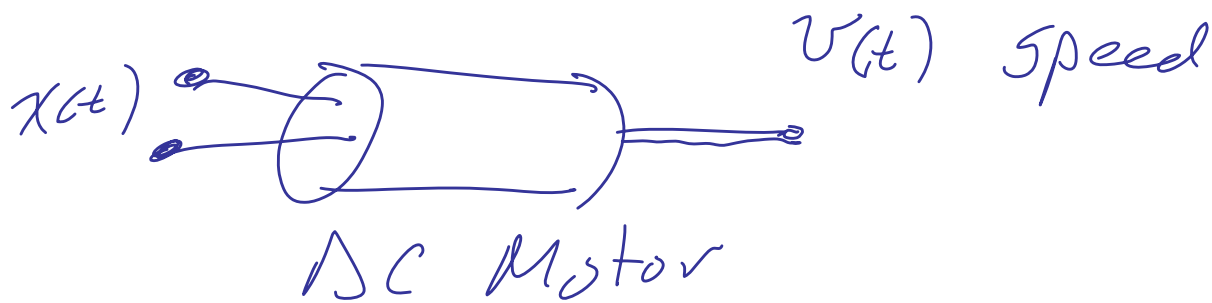


Example of LT Analysis



Recall from Discussion #3 we found the Diff. Eq. for the speed of a DC motor with an applied voltage $X(t)$:

$$\frac{d^2 v(t)}{dt^2} + \left(\frac{R}{L} + \frac{b}{F}\right) \frac{dv(t)}{dt} + \left(\frac{K_e K_t + R_b}{L F}\right) v(t) = \frac{K_t}{L F} X(t)$$

This can be written as:

$$\frac{d^2 v(t)}{dt^2} + a_1 \frac{dv(t)}{dt} + a_0 v(t) = b_0 X(t)$$

These depend on motor parameters

Now... Assume the motor is not turning (zero IC's)
& take LT:

$$H(s) = \frac{b_0}{s^2 + a_1 s + a_0}$$

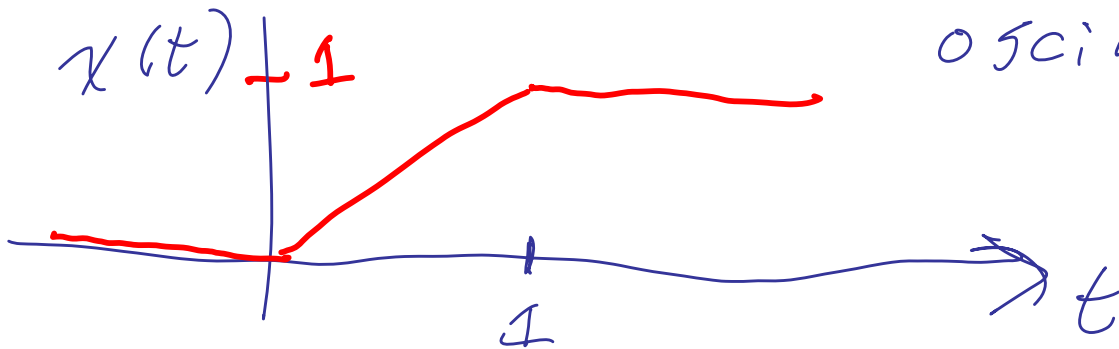
(B)

Assume that the motor parameters evaluate to

$$H(s) = \frac{18}{s^2 + 0.6s + 9} \rightarrow \text{complex roots}$$

Consider:

\Rightarrow expect oscillation!



Intent: Linearly accelerate the motor up to speed then hold steady speed.

$$x(t) = t u(t) - (t-1) u(t-1)$$

From LT Tables:

①

$$X(s) = \frac{1}{s^2} - \frac{1}{s^2} e^{-s}$$

$$Y(s) = H(s) X(s)$$

$$= \frac{H(s)}{s^2} - \underbrace{\frac{H(s)}{s^2} e^{-s}}_{\text{Delay of this}}$$

$$\text{Find } \mathcal{L}^{-1} \left\{ \frac{H(s)}{s^2} \right\}$$

$$\begin{aligned} \frac{H(s)}{s^2} &= \frac{18}{s^2 (s^2 + 0.6s + 9)} \\ &= \frac{18}{s^4 + 0.6s^3 + 9s^2} \end{aligned}$$

$s^2 + 2\zeta\omega_n s + \omega_n^2$
 $\zeta = 0.1$
"Damping"

Do Partial Fractions via MATLAB:

$$\frac{H(s)}{s^2} = \frac{-0.13}{s} + \frac{2}{s^2} + \frac{0.0667 + j0.33}{s + 0.3 - j2.99} + \frac{0.0667 - j0.33}{s + 0.3 + j2.99}$$

$\downarrow \mathcal{L}^{-1}\{ \}$

$$y_1(t) =$$

$$-0.13u(t) + 2tu(t) + \left(0.34 e^{+j1.37} \right) e^{-0.3t} e^{+j2.99t}$$

$$+ \left(0.34 e^{-j1.37} \right) e^{-0.3t} e^{-j2.99t}$$

Euler!

$$= -0.13u(t) + 2tu(t) + 0.34 e^{-0.3t} \cos(2.99t + 1.37)$$

The other part is just a delay:

$$y_2(t) = y_1(t-1)$$

$$\text{d } y(t) = y_1(t) - y_1(t-1)$$

The response looks like this:



Now, the overshoot occurs because we' the ζ is too low ($\zeta = 0.1$)

The parameter " b " provides more damping:

$$\frac{d^2 v(\alpha)}{dt^2} + \left(\frac{R}{L} + \frac{b}{J} \right) \frac{dv(\alpha)}{dt} + \left(\frac{K_e K_t + R_b}{LJ} \right) v(\alpha) = \frac{K_t}{LJ} \chi(\alpha)$$

Suppose we increased ζ to give

$$H(s) = \frac{18}{s^2 + 7s + 9}$$

↪ was 0.6, now is 7

The a similar analysis leads

to:

↪ ↪ "LAG" or "sluggishness"

