

Alternate Form for CRLB

$$\text{var}(\hat{\theta}) \geq \frac{1}{E \left\{ \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right]^2 \right\}}$$

See Appendix 3A
for Derivation

Sometimes it is easier to find the CRLB this way.

This also gives a new viewpoint of the CRLB:

Posted
on BB

From Gardner's Paper (*IEEE Trans. on Info Theory*, July 1979)

Consider the Normalized version of this form of CRLB

$$\frac{\text{var}(\hat{\theta})}{\theta^2} \geq \frac{1}{\theta^2 E \left\{ \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right]^2 \right\}}$$

We'll "derive"
this in a way
that will re-
interpret the
CRLB

Consider the “Incremental Sensitivity” of $p(\mathbf{x}; \theta)$ to changes in θ :

If $\theta \rightarrow \theta + \Delta\theta$, then it causes $p(\mathbf{x}; \theta) \rightarrow p(\mathbf{x}; \theta + \Delta\theta)$

How sensitive is $p(\mathbf{x}; \theta)$ to that change??

$$\tilde{S}_\theta^p(\mathbf{x}) \triangleq \frac{\left[\frac{\Delta p(\mathbf{x}; \theta)}{p(\mathbf{x}; \theta)} \right]}{\left[\frac{\Delta\theta}{\theta} \right]} = \frac{\% \text{ change in } p(\mathbf{x}; \theta)}{\% \text{ change in } \theta} = \left[\frac{\Delta p(\mathbf{x}; \theta)}{\Delta\theta} \right] \left[\frac{\theta}{p(\mathbf{x}; \theta)} \right]$$

Now let $\Delta\theta \rightarrow 0$: $S_\theta^p(\mathbf{x}) = \lim_{\Delta\theta \rightarrow 0} \tilde{S}_\theta^p(\mathbf{x}) = \left[\frac{\partial p(\mathbf{x}; \theta)}{\partial \theta} \right] \left[\frac{\theta}{p(\mathbf{x}; \theta)} \right] = \theta \frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta}$

Recall from Calculus: $\frac{\partial \ln f(x)}{\partial x} = \frac{1}{f(x)} \frac{\partial f(x)}{\partial x}$

$$\frac{\text{var}(\hat{\theta})}{\theta^2} \geq \frac{1}{\theta^2 E \left\{ \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right]^2 \right\}} = \frac{1}{\theta^2 E \left\{ \left[S_\theta^p(\mathbf{x}) \right]^2 \right\}}$$

Interpretation
 Norm. CRLB =
 Inverse Mean
 Square
 Sensitivity

Definition of Fisher Information

The denominator in CRLB is called the Fisher Information $I(\theta)$

It is a measure of the “expected goodness” of the data for the purpose of making an estimate

$$I(\theta) = -E \left\{ \frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right\}$$

Has the needed properties for “info” (as does “Shannon Info”):

1. $I(\theta) \geq 0$ (easy to see using the alternate form of CRLB)
2. $I(\theta)$ is additive for independent observations

follows from: $\ln p(\mathbf{x}; \theta) = \ln \left[\prod_n p(x[n]; \theta) \right] = \sum_n \ln [p(x[n]; \theta)]$

If each $I_n(\theta)$ is the same: $I(\theta) = N \times I(\theta)$

3.5 CRLB for Signals in AWGN

When we have the case that our data is “signal + AWGN” then we get a simple form for the CRLB:

$$\text{Signal Model: } x[n] = s[n; \theta] + w[n], \quad n = 0, 1, 2, \dots, N-1$$

White,
Gaussian,
Zero Mean

Q: What is the CRLB?

First write the likelihood function:

$$p(\mathbf{x}; \theta) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp\left\{ \frac{-1}{2\sigma^2} \sum_{n=0}^{N-1} (x[n] - s[n; \theta])^2 \right\}$$

Differentiate Log LF twice to get:

$$\frac{\partial^2}{\partial \theta^2} \ln p(\mathbf{x}; \theta) = \frac{1}{\sigma^2} \sum_{n=0}^{N-1} \left\{ (x[n] - s[n; \theta]) \frac{\partial^2 s[n; \theta]}{\partial \theta^2} - \left[\frac{\partial s[n; \theta]}{\partial \theta} \right]^2 \right\}$$

Depends on
random $x[n]$
so must take
 $E\{\}$

$$E \left\{ \frac{\partial^2}{\partial \theta^2} \ln p(\mathbf{x}; \theta) \right\} = \frac{1}{\sigma^2} \sum_{n=0}^{N-1} \left\{ \underbrace{\left(\frac{E\{x[n]\}}{s[n; \theta]} - s[n; \theta] \right)}_{=0} \frac{\partial^2 s[n; \theta]}{\partial \theta^2} - \left[\frac{\partial s[n; \theta]}{\partial \theta} \right]^2 \right\}$$

$$= \frac{- \sum_{n=0}^{N-1} \left[\frac{\partial s[n; \theta]}{\partial \theta} \right]^2}{\sigma^2}$$

Then using this we get the **CRLB for Signal in AWGN**:

$$\text{var}(\hat{\theta}) \geq \frac{\sigma^2}{\sum_{n=0}^{N-1} \left[\frac{\partial s[n; \theta]}{\partial \theta} \right]^2}$$

Note: $\left[\frac{\partial s[n; \theta]}{\partial \theta} \right]^2$ tells how
sensitive signal is to parameter

If signal is very sensitive to parameter change... then CRLB is small
... can get very accurate estimate!

Ex. 3.5: CRLB of Frequency of Sinusoid

Signal Model: $x[n] = A \cos(2\pi f_o n + \phi) + w[n]$ $0 < f_o < \frac{1}{2}$ $n = 0, 1, 2, \dots, N - 1$

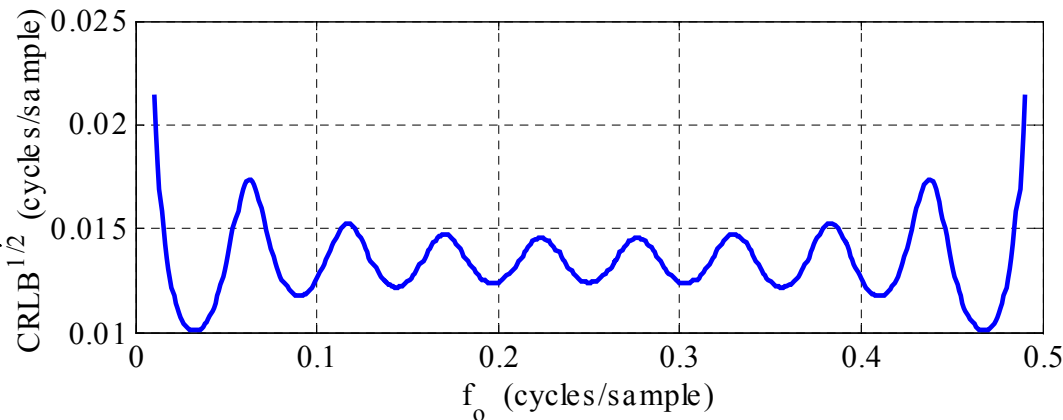
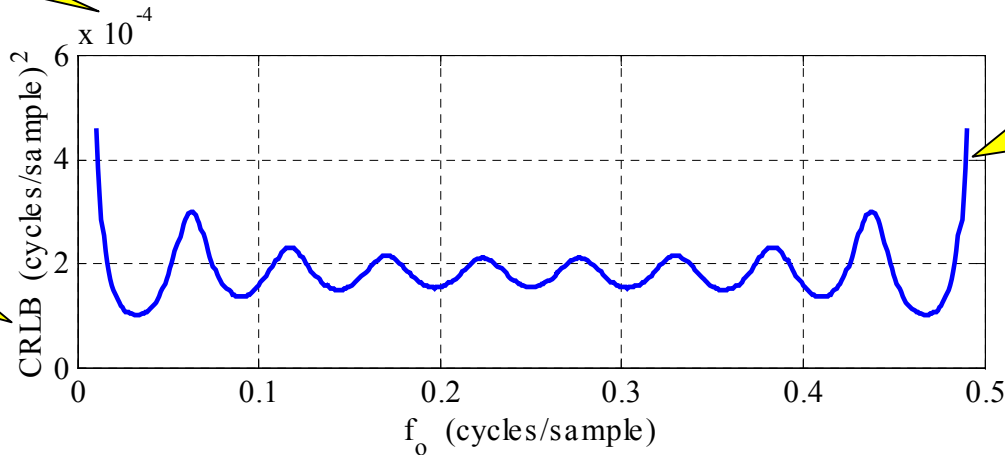
$$\text{var}(\hat{\theta}) \geq \frac{1}{\text{SNR} \times \sum_{n=0}^{N-1} [2\pi n \sin(2\pi f_o n + \phi)]^2}$$

Error in Book

Bound on Variance

Bound on Std. Dev.

Signal is less sensitive if f_o near 0 or $\frac{1}{2}$



3.6 Transformation of Parameters

Say there is a parameter θ with known $CRLB_{\theta}$

But imagine that we instead are interested in estimating some other parameter α that is a function of θ :

$$\alpha = g(\theta)$$

Q: What is $CRLB_{\alpha}$?

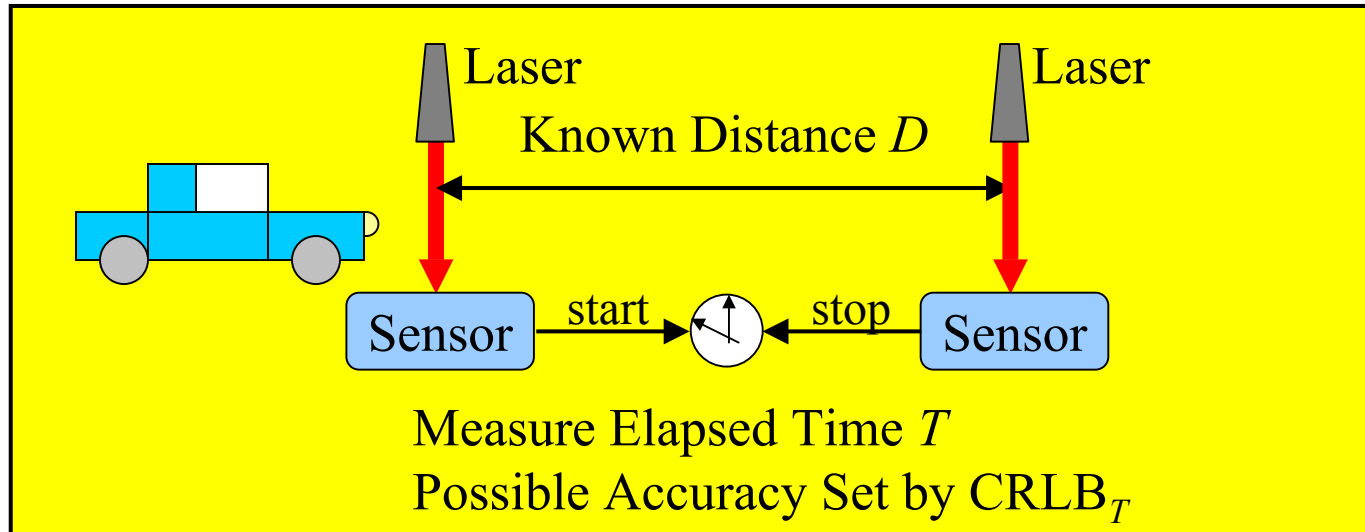
$$\text{var}(\alpha) \geq CRLB_{\alpha} = \left(\frac{\partial g(\theta)}{\partial \theta} \right)^2 CRLB_{\theta}$$

Proved in
Appendix 3B

Captures the
sensitivity of α to θ

**Large $\partial g / \partial \theta$ \rightarrow small error in θ gives larger error in α
 \rightarrow increases CRLB (i.e., worsens accuracy)**

Example: Speed of Vehicle From Elapsed Time



But... really want to measure speed $V = d/T$

Find the $CRLB_V$:

$$\begin{aligned} CRLB_V &= \left[\frac{\partial}{\partial T} \left(\frac{D}{T} \right) \right]^2 \times CRLB_T \\ &= \left(-\frac{D}{T^2} \right)^2 \times CRLB_T \\ &= \frac{V^4}{D^2} \times CRLB_T \end{aligned}$$

Accuracy Bound

$$\sigma_V \geq \frac{V^2}{D} \sqrt{CRLB_T} \quad (m/s)$$

- Less accurate at High Speeds (quadratic)
- More accurate over large distances

Effect of Transformation on Efficiency

Suppose you have an efficient estimator of θ : $\hat{\theta}$

But... you are really interested in estimating $\alpha = g(\theta)$

Suppose you plan to use $\hat{\alpha} = g(\hat{\theta})$

Q: Is this an efficient estimator of α ???

A: **Theorem**: If $g(\theta)$ has form $g(\theta) = \underbrace{a\theta + b}_{\text{“affine” transform}}$, then $\hat{\alpha} = g(\hat{\theta})$ is efficient.

“affine” transform

Proof:

First: $\text{var}(\hat{\alpha}) = \text{var}(a\hat{\theta} + b) = a^2 \text{var}(\hat{\theta}) = a^2 \text{CRLB}_\theta$

“=” because “efficient”

Now, what is CRLB_α ? Using transformation result:

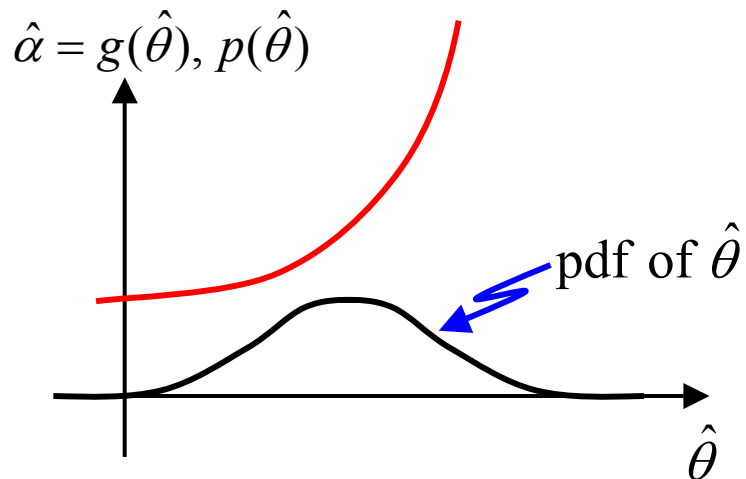
$$\text{CRLB}_\alpha = \underbrace{\left[\frac{\partial(a\theta + b)}{\partial\theta} \right]^2}_{=a^2} \text{CRLB}_\theta = a^2 \text{CRLB}_\theta \longrightarrow \boxed{\text{var}(\hat{\alpha}) = \text{CRLB}_\alpha}$$

Efficient!

Asymptotic Efficiency Under Transformation

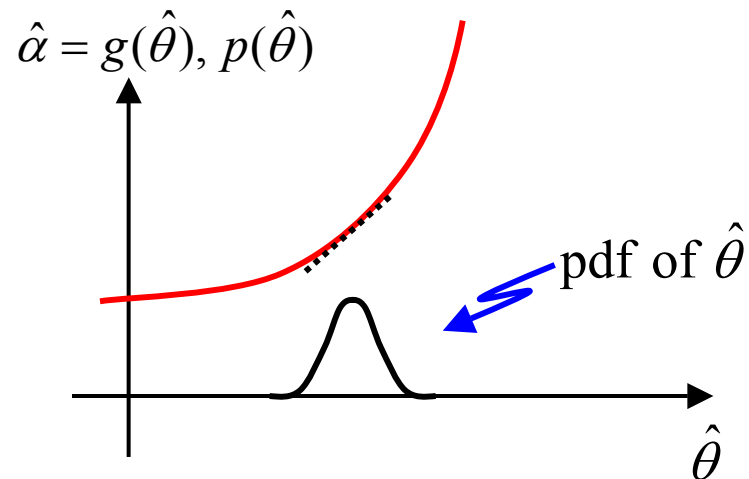
If the mapping $\alpha = g(\theta)$ is not affine... this result does NOT hold

But... if the number of data samples used is large, then the estimator is approximately efficient (“Asymptotically Efficient”)



Small N Case

PDF is widely spread
over nonlinear mapping



Large N Case

PDF is concentrated
onto linearized section