

# Ch. 10 Vector Quantization

## Advantages & Design

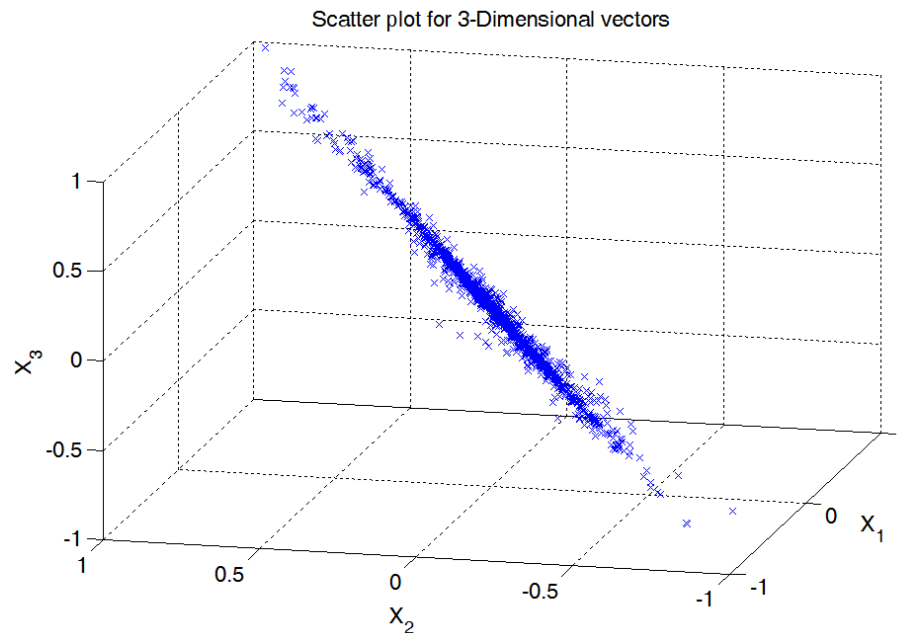
# Advantages of VQ

There are (at least) 3 main characteristics of VQ that help it outperform SQ:

1. Exploit Correlation within vectors
  2. Exploit Shape Flexibility in  $L$ -D space
  3. Achieve Fractional Bits per sample
- } **Helpful even when source is IID**

**1. Correlation** – Correlation leads to regions in  $L$ -D space where vectors are very unlikely to occur...

- Put big cells where vectors are unlikely
- Put small cells where vectors are likely

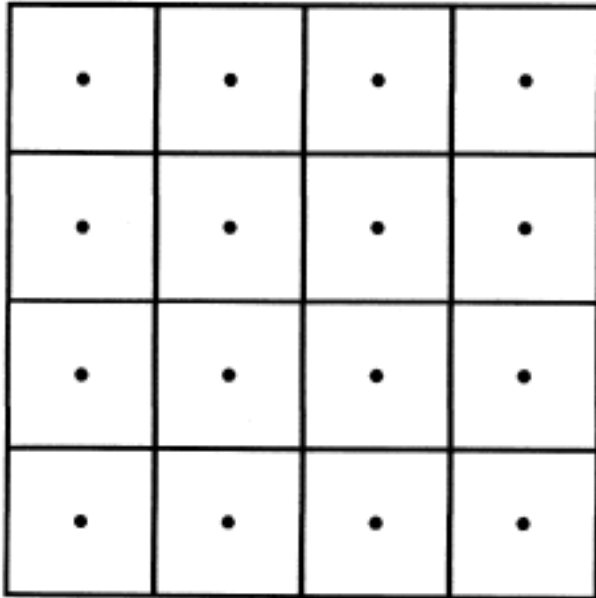


**2. Shape Gain** – Uniform SQ equivalent in  $L$ -D space gives cells that are  $L$ -D hypercubes...

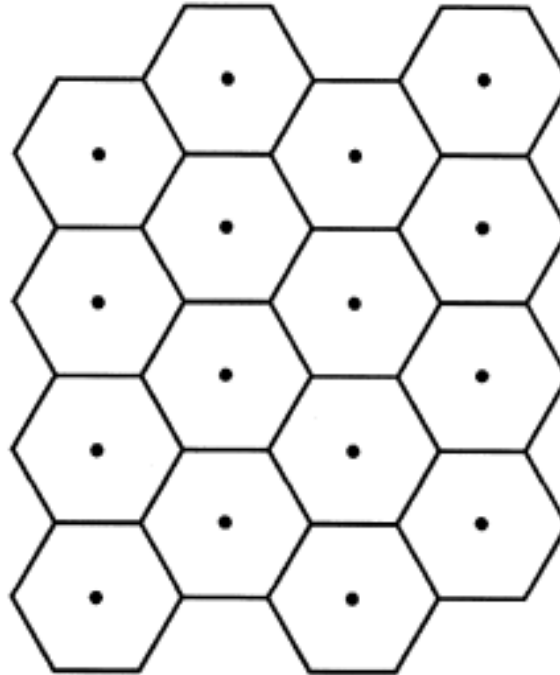
→ VQ cells can be any shape

→ Leads to lower distortion for same rate

SQ Equivalent in 2-D Space



2-D VQ using Hexagonal Cells

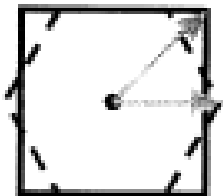


**Both of these have the same density of RLS... Both have Same Rate**

**→ Hexagonal shaped cells give “shape gain”**

**Shape Gain helps even for IID!!!**

**→ VQ is ALWAYS better than SQ**



**Square cells have larger distortion since maximum distance from center is larger than for hexagon**

### 3. Fractional Bits – The # of bits must always be an integer for SQ

- Doesn't allow fine degree of choice of rate
- This is especially true at low rates

Example: Say original A/D-sampled signal uses  $B = 12$  bits/sample

Compress further using SQ

If we use 3-bit SQ →  $CR = 12/3 = 4:1$

If we use 2-bit SQ →  $CR = 12/2 = 6:1$

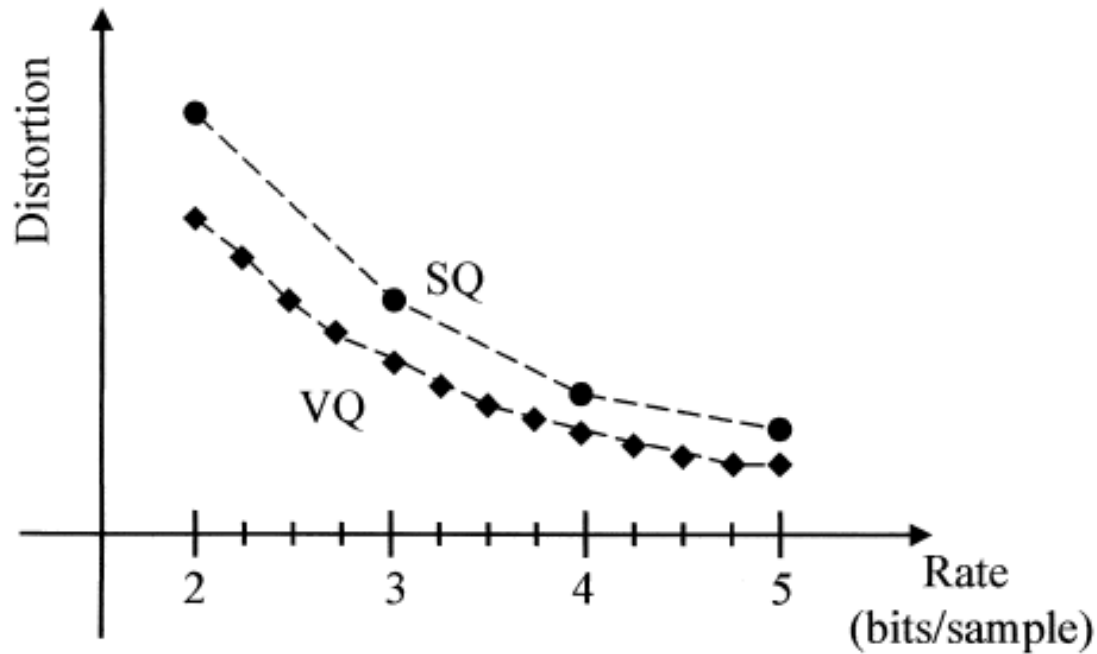
Can't get any CR between these when using SQ

But with VQ we can...

Consider  $L = 4$  for the VQ Dimension...

$M$	bits/vector = $\log_2 M$	bits/sample = $(\log_2 M)/L$	$CR = B/[(\log_2 M)/L]$
256	8	2.00	6.00
512	9	2.25	5.33
1024	10	2.50	4.80
2048	11	2.75	4.36
4096	12	3.00	4.00

Due to the ability to use fractional bits/sample...  
VQ gives more flexibility to trade-off R & D



VQ gives more flexibility to trade-off  
R & D due to fractional bits/sample

# Designing an $L$ -D VQ

Note: Despite potential confusion... I use the same symbol here to represent the random vector and the dummy-variable vector

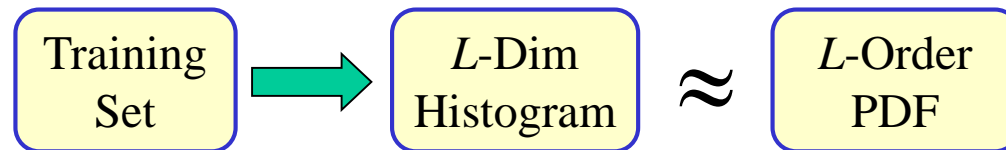
**In Theory**: Given an  $L$ -order PDF of the signal... i.e.,  $f_{\mathbf{x}}(\mathbf{x})$

Can design an  $L$ -D VQ using a vector version of the Lloyd-Max method that was given for SQ

**In Practice**: Don't know the  $L$ -order PDF  $f_{\mathbf{x}}(\mathbf{x})$ !!!

Use a training set of representative signals

This can be viewed in essence as:




**But**... we will use the training set in a more direct way to design an  $L$ -D VQ

# Linde-Buzo-Gray (LBG) Design

$L$  is VQ  
Dimension

Recall: VQ Design = Specifying  $M$  reconstruction points

Let  $x_1[n], x_2[n], \dots, x_p[n]$  be  $p$  signals in the training set.

Break each signal into  $L$ -pt. blocks (non-overlapping) too get  $N$  training vectors (want  $N$  to be large).  **Training Vectors:**  $\{\mathbf{x}_n\}_{n=1}^N$

## Steps in Design

1. **Choose Initial Recon. Vectors:**  $\{\mathbf{y}_i^{(0)}\}_{i=1}^M$

- This choice is important... but for now we'll ignore how we do it

**Initialize**  $\{\mathbf{y}_i^{(0)}\}_{i=1}^M$   Initial RLs

Book Error...  
uses  $D^{(0)}$  instead...

$k = 0$   Iteration Counter

$D^{(-1)} = 0$   Initial Distortion

$\varepsilon < 1$   Termination Threshold

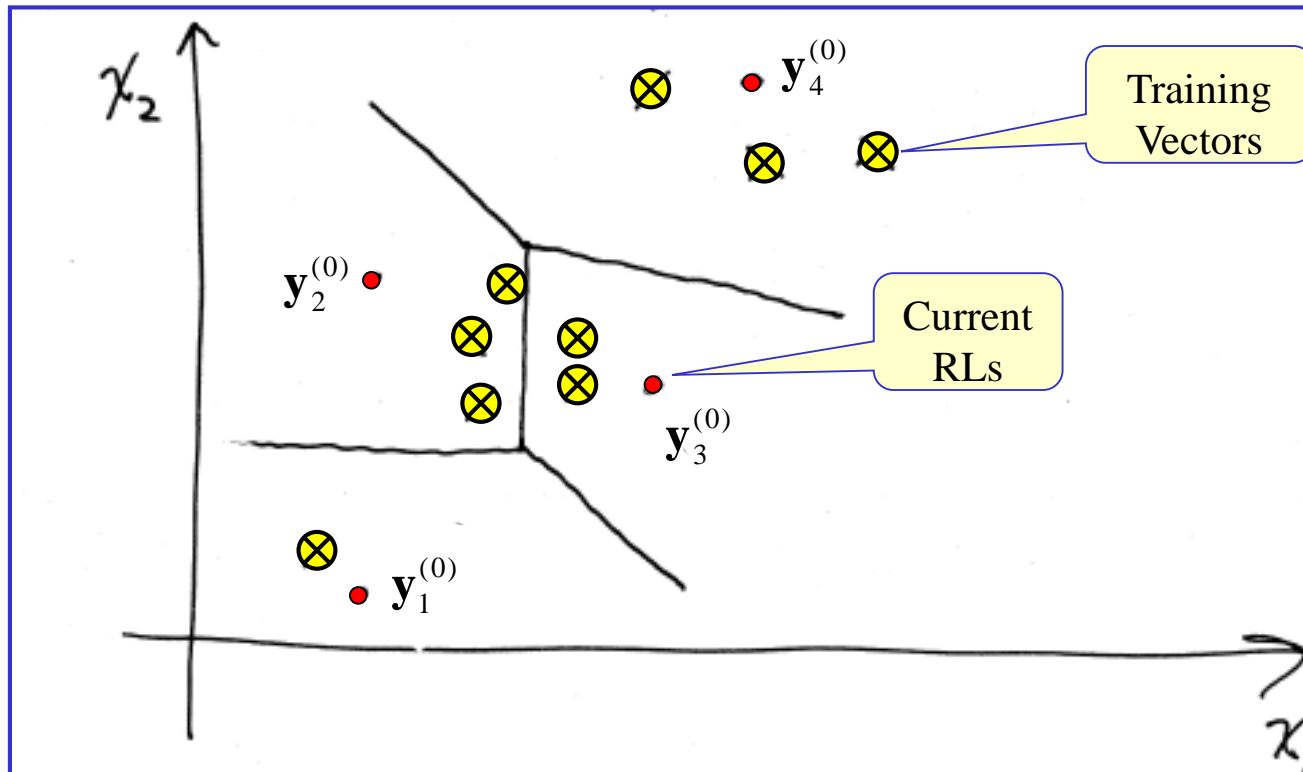
## 2. Find Quantization Clusters: $\{V_i^{(k)}\}_{i=1}^M$

Each  $V_i^{(k)}$  is a set of training vectors clustered around current iteration RL  $\mathbf{y}_i^{(k)}$

Definition of Clusters:

$$V_i^{(k)} = \{\mathbf{x}_n : d(\mathbf{x}_n, \mathbf{y}_i) < d(\mathbf{x}_n, \mathbf{y}_j), \forall j \neq i\}, \quad i = 1, 2, \dots, M$$

(For now, assume no  $V_i^{(k)}$  is empty... deal with the empty cell problem later)



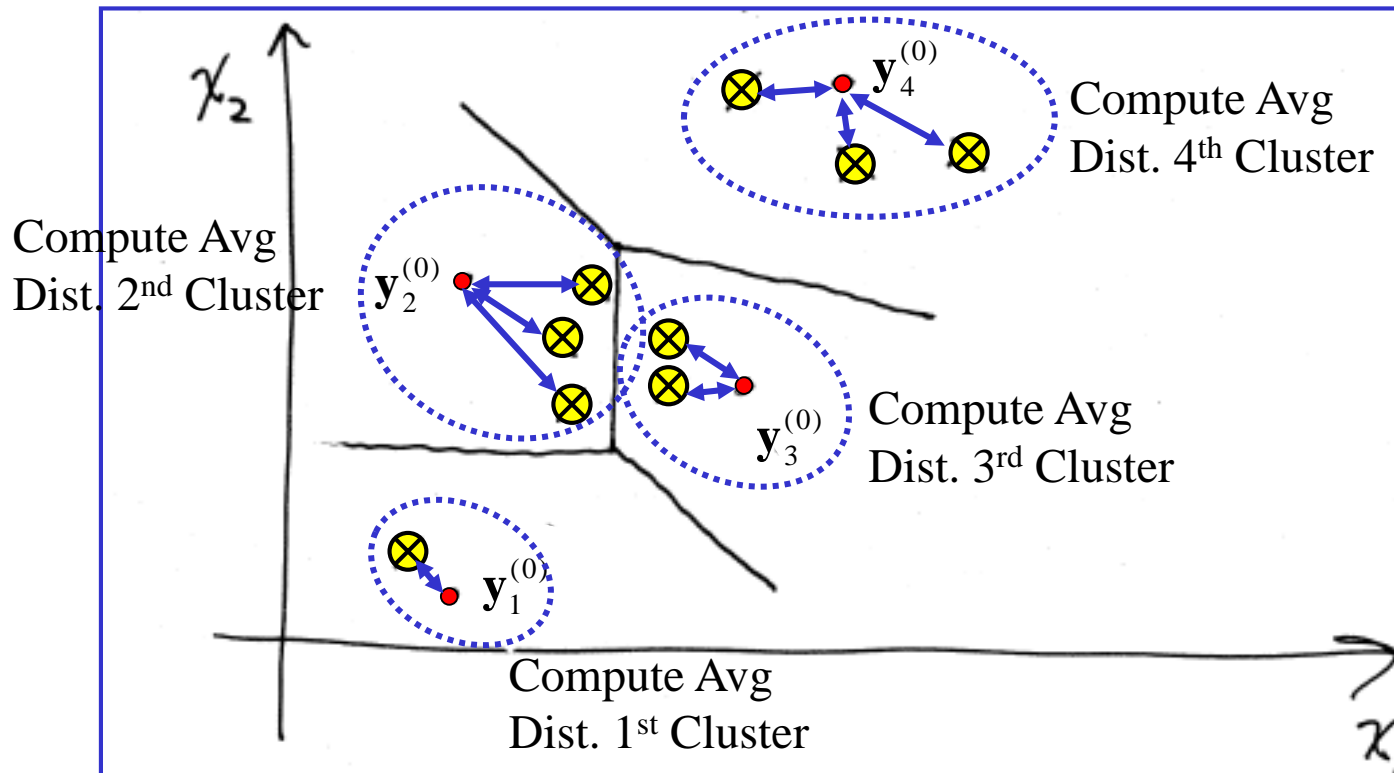


### 3. Compute Resulting Distortion: “Finding Goodness of Current RLs”

For each cluster let  $N_i^{(k)} = \#$  elements in  $V_i^{(k)}$  and compute:

$$D^{(k)} = \frac{1}{NM} \sum_{i=1}^M \left[ \sum_{\mathbf{x}_n \in V_i^{(k)}} \left\| \mathbf{x}_n - \mathbf{y}_i^{(k)} \right\|^2 \right]$$

$N$  vectors in  $M$  dimensions  $\rightarrow NM$  samples



#### 4. Check for Convergence: *Stop if Change in Distortion is Small*

Stop if: 
$$\frac{|D^{(k)} - D^{(k-1)}|}{D^{(k)}} < \varepsilon$$

Note that  $D^{(-1)} = 0$  and  $\varepsilon < 1$  ensures the first iteration's test checks if  $1 < \varepsilon$  and therefore can't stop on 1<sup>st</sup> iteration

Otherwise, Continue...

## 5. Update RLs: *Find Better Reconstruction Vectors*

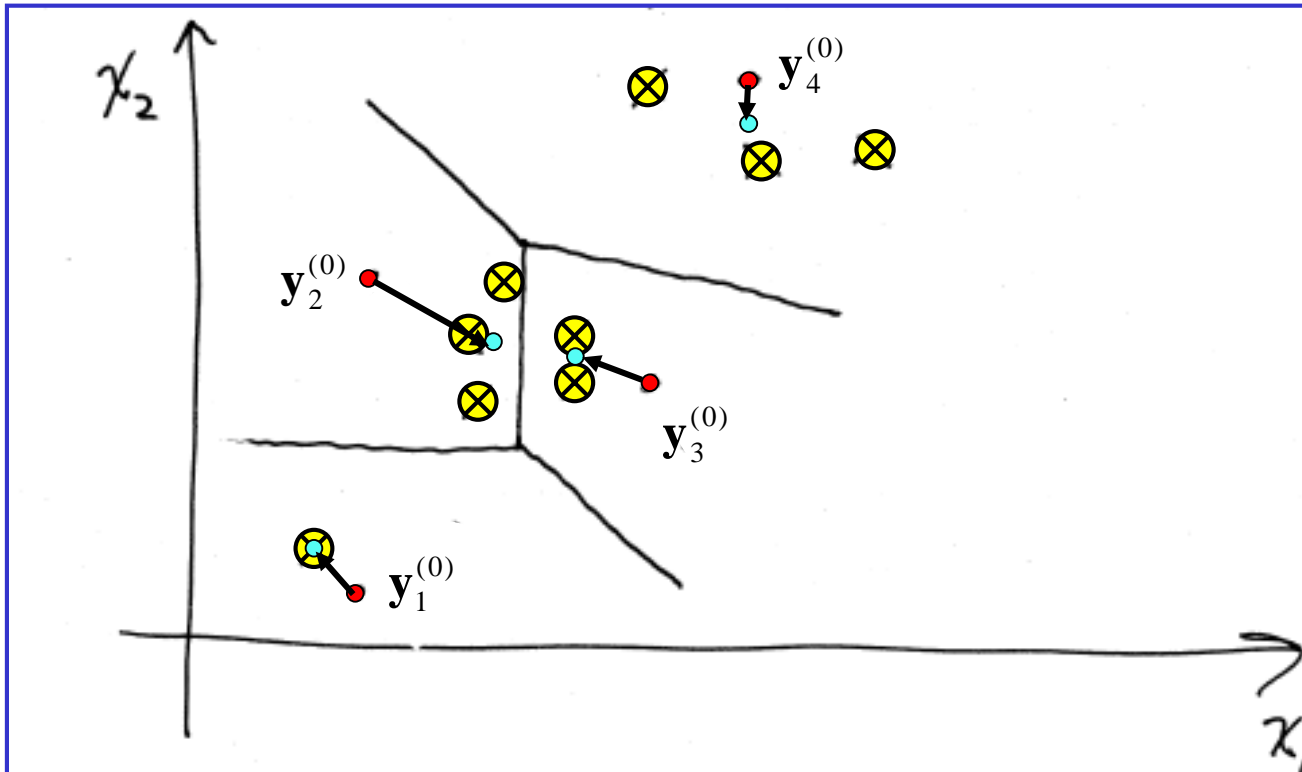
– Set  $k = k + 1$

– For each  $i = \{1, 2, \dots, M\}$  compute  $\mathbf{y}_i^{(k)} = \text{Avg} \{ \mathbf{x}_n \in V_i^{(k-1)} \}$

New RLs are  
Centroids of Clusters

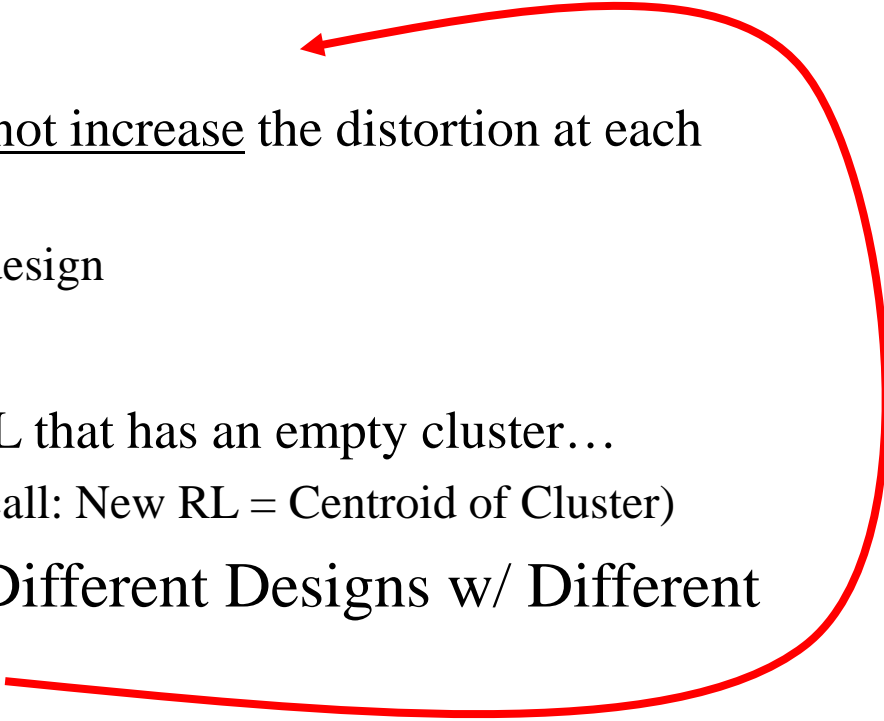
$$= \frac{1}{N_i^{(k)}} \sum_{\mathbf{x}_n \in V_i^{(k)}} \mathbf{x}_n$$

Data  
Averaging



Go To Step #2

# Problems With LBG Design

- **LBG Finds Local Minimum**
    - Although LBG is guaranteed to not increase the distortion at each iteration...
      - ...it may not yield the optimal design
  - **Empty Cell Problem**
    - If in some iteration there is an RL that has an empty cluster...
      - You can't find an a new RL (recall: New RL = Centroid of Cluster)
  - **Different Initializations Give Different Designs w/ Different Performance**
    - This is linked to this problem...
- 

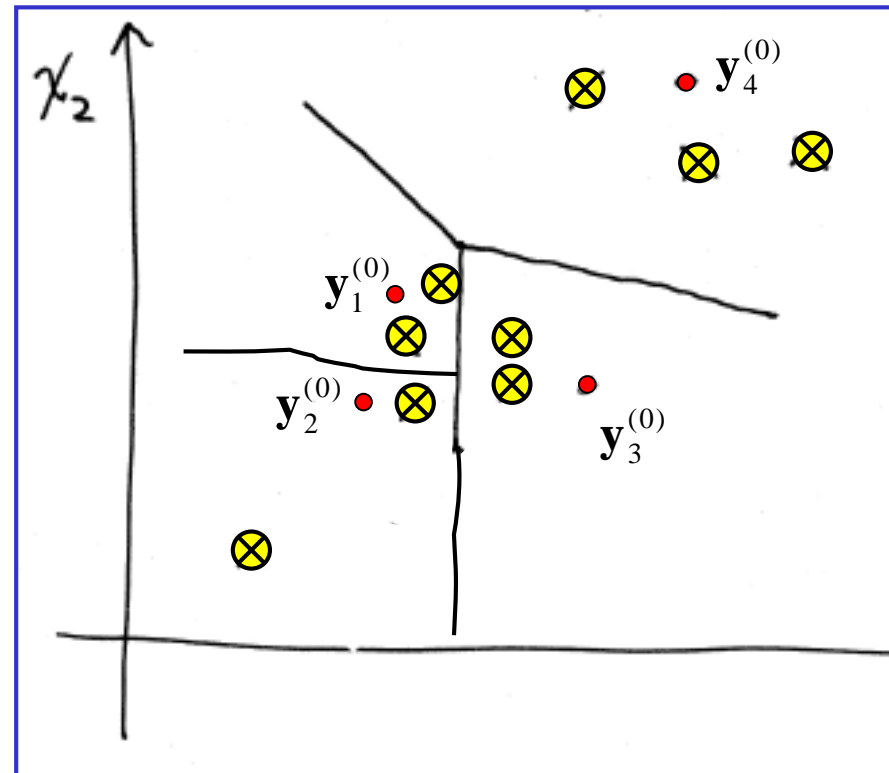
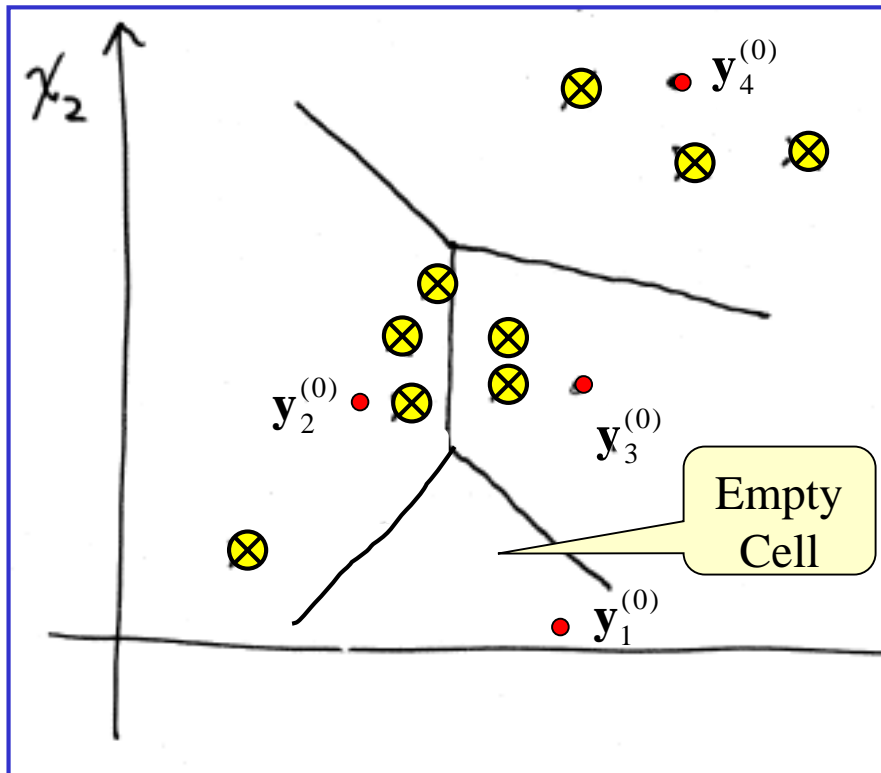
## Empty Cell Problem

If in Step #2 (*Find Clusters*) some RL  $\mathbf{y}_i^{(k)}$  gets no cluster, then  $V_i^{(k)}$  is empty

Then, in Step #5 (*Update RLs*) you can't find a new RL...

→ Loss of an RL reduces the “Designed-to” Rate of the VQ... Not Desirable

**Solution:** In Step #2... Replace the empty cell's  $\mathbf{y}_i^{(k)}$  with a new RL randomly placed inside the *most populous* cell... then, re-cluster and proceed.



# Initialization

Different initial RLs give different designs... w/ different perform.

## Four Alternative Approaches

### 1. Splitting

- Start w/  $M = 1$  (i.e., a 1-level VQ) and use LBG to design the VQ
- Randomly split the level (small perturbation) to get 2 RLs
  - Now,  $M = 2$  ... Run LBG to design  $M = 2$  VQ
- Split again and again to get  $M = 4, 8, 16, 32$ , etc...

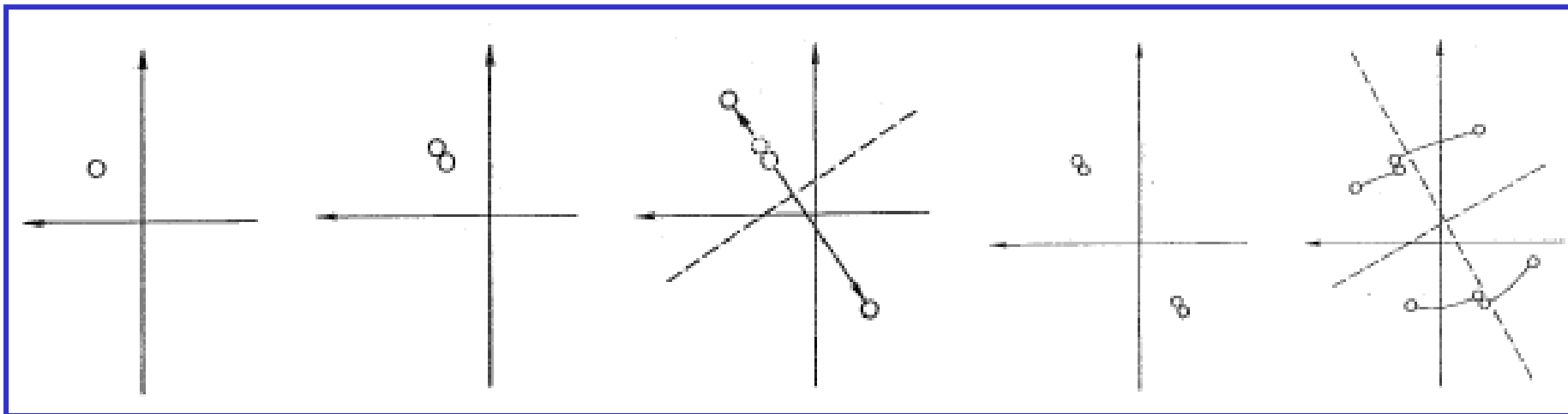
$M = 1$

Perturbed,  $M = 2$

LBG'd,  $M = 2$

Perturbed,  $M = 4$

LBG'd,  $M = 4$



From Gray's Paper on VQ in *IEEE ASSP Magazine*, April 1984

## 2. Randomly Pick $M$ RLs from Training Vectors

- Randomly Pick  $M$  RLs
- Run LBG to get  $M$ -Level Design
- Repeat these two steps several times & pick the best resulting design

## 3. Use all Training Vect. as RLs and Combine to get Desired $M$

- Pair-wise Combine “Nearest Neighbors”
  - Paired to give smallest increase in Dist.
- Combine each pair into a single new RL = Avg of two in pair
- Repeat until # of RLs has decreased to Desired  $M$
- Use resulting  $M$  RLs as initial RLs for the LBG design

## 4. Design decent SQ for the prob. & form $L$ -D “Rect”-Grid VQ

- Use resulting rectangles’ centroids as initial RLs for LBG